Generalized mass action systems and positive solutions of polynomial systems

# $\mathsf{A} + \mathsf{B} \rightleftharpoons \mathsf{C}$

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# Chemical reaction network theory (CRNT)

Chemical reaction networks with mass-action kinetics (MAK) give rise to polynomial ODE systems with positive parameters

CRNT:

Uniqueness and existence of positive steady states

- independent of parameters (rate constants)
- depending only on network properties

Corresponding polynomial systems with positive parameters:

Uniqueness and existence of positive real solutions

- independent of parameters

generalized mass-action kinetics depending on the relation between coefficients and exponents

## Mass-action kinetics (MAK)

Reaction:

 $1\,A+1\,B\rightarrow C$ 

A, B ... reactant *species* C ... product species

MAK reaction rate:

$$v = k c_A^1 c_B^1$$

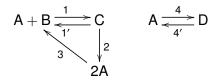
 $k > 0 \dots rate \ constant$  $c_A = c_A(t) \ge 0 \dots concentration \ of \ A$ 

Contribution to network dynamics:

$$\frac{\mathrm{d}}{\mathrm{d}t} \begin{pmatrix} c_{\mathrm{A}} \\ c_{\mathrm{B}} \\ c_{\mathrm{C}} \\ \vdots \end{pmatrix} = k c_{\mathrm{A}} c_{\mathrm{B}} \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + \cdots$$

## Chemical reaction networks

#### Example:



A+B, C, 2A, A, D . . . complexes

Dynamics for rate constants  $k = (k_1, k_{1'}, k_2, k_3, k_4, k_{4'})$ :

$$\frac{\mathrm{d}c}{\mathrm{d}t} = \frac{\mathrm{d}}{\mathrm{d}t} \begin{pmatrix} c_{\mathrm{A}} \\ c_{\mathrm{B}} \\ c_{\mathrm{C}} \\ c_{\mathrm{D}} \end{pmatrix} = \begin{pmatrix} -1 & 2 & -1 & -1 \\ -1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} k_1 c_{\mathrm{A}} c_{\mathrm{B}} - k_{1'} c_{\mathrm{C}} \\ k_2 c_{\mathrm{C}} \\ k_3 c_{\mathrm{A}}^2 \\ k_4 c_{\mathrm{A}} - k_{4'} c_{\mathrm{D}} \end{pmatrix} = N v_k(c)$$

 $N \dots$  stoichiometric matrix  $v_k \dots$  net reaction rates

# Deficiency

#### Example:

1	4	(-1	2	-1	-1)
$A + B \xrightarrow{1} C$	A  D	$N = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix}$	0	1	0
1' $2$	4′	N = 1	-1	0	0
·		lo	0	0	1)
2A					

## Definition

A network is *weakly reversible* if each connected component is strongly connected. Its *deficiency* is given by

$$\delta = m - \ell - s.$$

*m*...number of complexes

 $\ell \dots$  number of connected components

 $s \dots$  dimension of stoichiometric subspace S = im(N)

$$\delta = 5 - 2 - 3 = 0$$

# Deficiency zero theorem

Dynamics:

$$\frac{\mathrm{d}c}{\mathrm{d}t} = N \, v_k(c)$$

$$\Rightarrow$$
  $c(t) \in (c(0) + S)$  with  $S = im(N)$ 

 $(c(0) + S)_{\geq 0} \dots$  stoichiometric compatibility class

#### Theorem

A reaction network with zero deficiency has a unique asymptotically stable positive steady state in each stoichiometric compatibility class for all positive rate constants if and only if it is weakly reversible.

(Horn-Jackson '72, Horn '72, Feinberg '72)

## Deficiency zero theorem

#### Example:

$$N v_k(c) = \begin{pmatrix} -1 & 2 & -1 & -1 \\ -1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} k_1 c_A c_B - k_{1'} c_C \\ k_2 c_C \\ k_3 c_A^2 \\ k_4 c_A - k_{4'} c_D \end{pmatrix} = 0$$

Deficiency zero theorem  $\Rightarrow$  unique positive steady state  $Nv_k(c) = 0$ in each stoichiometric compatibility class for all rate constants

Polynomial equations with parameters:

$$\{c > 0 \mid N v_k(c) = 0\} \cap (c' + S)_{\geq 0}$$

contains exactly one element for all c' > 0 and all k > 0

## **Graph Laplacian**

#### Minimal example:

$$A + B \underset{1'}{\stackrel{1}{\rightleftharpoons}} C$$

Dynamics:

$$\frac{\mathrm{d}c}{\mathrm{d}t} = \begin{pmatrix} -1\\ -1\\ 1 \end{pmatrix} \left( k_1 \ c_{\mathrm{A}} c_{\mathrm{B}} - k_1' \ c_{\mathrm{C}} \right) = N \ v_k(c)$$

Decomposition:

$$\frac{\mathrm{d}c}{\mathrm{d}t} = \begin{pmatrix} 1 & 0\\ 1 & 0\\ 0 & 1 \end{pmatrix} \begin{pmatrix} -k_1 & k_{1'}\\ k_1 & -k_{1'} \end{pmatrix} \begin{pmatrix} c_{\mathrm{A}}c_{\mathrm{B}}\\ c_{\mathrm{C}} \end{pmatrix} = Y A_k \Psi(c)$$

(Horn-Jackson '72)

 $A_k \dots$  weighted graph Laplacian

# Complex balancing equilibria

Decomposition:

$$\frac{\mathrm{d}c}{\mathrm{d}t} = Y A_k \psi(c)$$

Complex balancing equilibria:

$$Z_k = \{c > 0 \, | \, A_k \, \psi(c) = 0\}$$

Deficiency:

$$\delta = \dim(\ker(Y) \cap \operatorname{im}(A_k))$$

Parametrization of complex balancing equilibria:

#### Proposition

$$\boldsymbol{c}^* \in \boldsymbol{Z}_k \neq \emptyset \quad \Rightarrow \quad \boldsymbol{Z}_k = \left\{ \boldsymbol{c}^* \circ \boldsymbol{e}^{\boldsymbol{v}} = \left( \boldsymbol{c}_1^* \, \boldsymbol{e}_1^{\boldsymbol{v}}, \dots, \boldsymbol{c}_n^* \, \boldsymbol{e}_n^{\boldsymbol{v}} \right) \mid \boldsymbol{v} \in \boldsymbol{S}^{\perp} \right\}_{(Horn-Jackson \, {}^{\prime}\boldsymbol{Z}\boldsymbol{2})}$$

Monomial param.:  $Z_k = \{ c^* \circ x^W = (c_1 x^{w^1}, ..., c_n x^{w^n}) | x \in \mathbb{R}^d \}$ 

with  $W = (w^1, \ldots, w^n) \in \mathbb{R}^{d \times n}$  of rank d s.t. S = ker(W)

$$S = \ker(W)$$
 with  $W = (w^1, \dots, w^n) \in \mathbb{R}^{d \times n}$ 

Existence/uniqueness of complex balancing equilibria in each stoichiometric compatibility class, that is, exactly one element in

$$\left\{\boldsymbol{c}^* \circ \boldsymbol{x}^{\boldsymbol{W}} \,|\, \boldsymbol{x} \in \mathbb{R}^d_{>}\right\} \cap \left(\boldsymbol{c}' + \ker(\boldsymbol{W})\right)$$

for all  $c^* > 0$  and  $c' > 0 \Leftrightarrow$  surjectivity/injectivity of

$$f_{\mathcal{C}^*} \colon \mathbb{R}^d_{>} \to \mathcal{C}^{\circ} \subseteq \mathbb{R}^d, \quad x \mapsto \sum_{k=1}^n c_k^* x^{w^k} w^k$$

for all  $c^* > 0$ , with the polyhedral cone

$$\boldsymbol{C} = \left\{ \sum_{k=1}^{n} \boldsymbol{C}_{k} \, \boldsymbol{w}^{k} \in \mathbb{R}^{d} \, | \, \boldsymbol{C} \in \mathbb{R}_{\geq}^{n} \right\}.$$

#### Theorem

The map  $f_{c^*}$  is a bijection (real analytic isomorphism) for all  $c^* > 0$ .

(Birch '63, Horn-Jackson '72, Fulton '93)

# Martin W. Birch

# M. W. Birch, Maximum likelihood in three-way contingency tables, *J. Roy. Statist. Soc. Ser. B* **25** (1963), 220–233.

Statistical Laboratory, University of Cambridge, 1961



Source http://www.statslab.cam.ac.uk/Dept/Photos/pic61.html

Martin W. Birch (1939-69)

## Birch's theorem

#### Minimal example:

$$S = \operatorname{im}(-1, -1, 1)^{T} = \operatorname{ker}(W)$$
  
with  $W = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ 

Birch's theorem  $\Rightarrow$  There exists a unique solution  $x \in \mathbb{R}^3_>$  for

$$c_1^* x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2^* x_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_3^* x_1 x_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

for all right-hand sides  $y \in \mathbb{R}^2_>$  and for all parameters  $c^* \in \mathbb{R}^3_>$ .

All mass action systems arising from

$$A + B \underset{1'}{\stackrel{1}{\rightleftharpoons}} C$$

have a unique positive steady state.

Mass action rate law is valid for elementary reactions in homogeneous and dilute solutions.

Intracellular environments are highly structured; more general reaction rates needed for applications in cell biology.

## Generalized mass action systems

Minimal example:

$$\begin{array}{ccc} \mathsf{A} + \mathsf{B} & \stackrel{1}{\overleftarrow{\leftarrow}} & \mathsf{C} \\ \vdots & & \vdots \\ \alpha \mathsf{A} + \beta \mathsf{B} & \gamma \mathsf{C} \end{array}$$

 $\alpha, \beta, \gamma > 0 \dots$  kinetic orders  $\alpha A + \beta B, \gamma C \dots$  kinetic complexes

Reaction rates:

$$v_1 = k_1 c^{\alpha}_A c^{\beta}_B$$
 and  $v_{1'} = k_{1'} c^{\gamma}_C$ 

Dynamics, decomposition:

$$\frac{\mathrm{d}c}{\mathrm{d}t} = \begin{pmatrix} 1 & 0\\ 1 & 0\\ 0 & 1 \end{pmatrix} \begin{pmatrix} -k_1 & k_{1'}\\ k_1 & -k_{1'} \end{pmatrix} \begin{pmatrix} c_{\mathsf{A}}^{\alpha} c_{\mathsf{B}}^{\beta}\\ c_{\mathsf{C}}^{\gamma} \end{pmatrix} = Y A_k \tilde{\psi}(c)$$

## Generalized mass action systems

$$\begin{array}{ccc} \mathbf{A} + \mathbf{B} & \stackrel{1}{\overleftarrow{\leftarrow}} & \mathbf{C} \\ \vdots & & \vdots \\ \alpha \mathbf{A} + \beta \mathbf{B} & \gamma \mathbf{C} \end{array}$$

Stoichiometric subspace:

$$N = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, \quad S = \operatorname{im}(N)$$

Kinetic-order subspace:

$$ilde{N} = \begin{pmatrix} -lpha \\ -eta \\ \gamma \end{pmatrix}, \quad ilde{S} = \operatorname{im}( ilde{N})$$

Complex balancing equilibria:

$$c^* \in \tilde{Z}_k = \left\{ c > 0 \,|\, A_k \, \tilde{\psi}(c) = 0 
ight\} \quad \Rightarrow \quad \tilde{Z}_k = \{ c^* \circ \mathbf{e}^v \mid v \in \tilde{S}^\perp \}$$

## Deficiency zero/Birch's theorem?

$$S = \ker(W)$$
 and  $\tilde{S} = \ker(\tilde{W})$   
with  $W = (w^1, \dots, w^n)$  and  $\tilde{W} = (\tilde{w}^1, \dots, \tilde{w}^n)$ 

Existence/uniqueness of complex balancing equilibria in each stoichiometric compatibility class, that is, exactly one element in

$$\{c^* \circ e^{v} \mid v \in \tilde{S}^{\perp}\} \cap (c' + S)$$

for all  $c^* > 0$  and  $c' > 0 \Leftrightarrow$  surjectivity/injectivity of the generalized polynomial map

$$f_{\mathcal{C}^*} \colon \mathbb{R}^d_{>} \to \mathcal{C}^{\circ} \subseteq \mathbb{R}^d, \quad x \mapsto \sum_{k=1}^n c_k^* x^{\widetilde{w}^k} w^k$$
 (gpm)

for all  $c^* > 0$ .

Deficiency zero theorem: 
$$S = \tilde{S}$$
  
Birch' theorem:  $\tilde{W} = W$ 

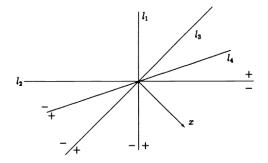
How much can we perturb the exponents/subspace/cone?

## Sign vectors

For  $x \in \mathbb{R}^n$ , obtain the sign vector  $\sigma(x) \in \{-, 0, +\}^n$  by applying the sign function componentwise:

$$\sigma \begin{pmatrix} \mathbf{1} \\ \mathbf{0} \\ -\mathbf{1} \end{pmatrix} = \begin{pmatrix} + \\ \mathbf{0} \\ - \end{pmatrix}$$

Point configurations, hyperplane arrangements, face lattices of cones Theory of *oriented matroids* 



#### Theorem

If 
$$\sigma(\tilde{S}) = \sigma(S)$$
 and  $(+, ..., +)^T \in \sigma(S^{\perp})$ ,  
then the generalized polynomial map  $f_{c^*}$ , defined in Eqn. (gpm),  
is a real analytic isomorphism for all  $c^* > 0$ .

### CRNT:

#### Theorem

If a reaction network with zero deficiency is weakly reversible and conservative, then there exists a unique positive steady state in each stoichiometric compatibility class, for all positive rate constants and all kinetic complexes with  $\sigma(\tilde{S}) = \sigma(S)$ .

## Generalized Birch's theorem

Minimal example:

$$S = \operatorname{im}(-1, -1, 1)^{T} \quad \text{and} \quad \tilde{S} = \operatorname{im}(-\alpha, -\beta, \gamma)^{T} \text{ with } \alpha, \beta, \gamma > 0$$
$$\sigma(S) = \left\{ \begin{pmatrix} -\\ -\\ + \end{pmatrix}, \begin{pmatrix} +\\ +\\ - \end{pmatrix}, \begin{pmatrix} 0\\ 0\\ 0 \end{pmatrix} \right\} = \sigma(\tilde{S}) \quad \text{and} \quad \begin{pmatrix} 1\\ 1\\ 2 \end{pmatrix} \in S^{\perp}$$
$$W = \begin{pmatrix} 1 & 0 & 1\\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad \tilde{W} = \begin{pmatrix} \gamma & 0 & \alpha\\ 0 & \gamma & \beta \end{pmatrix}$$

Theorem  $\Rightarrow$  There exists a unique solution  $x \in \mathbb{R}^3_>$  for

$$c_1^* x_1^{\gamma} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2^* x_2^{\gamma} \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_3^* x_1^{\alpha} x_2^{\beta} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

for all  $y \in \mathbb{R}^2_>$ , all parameters  $c^* \in \mathbb{R}^3_>$ , and all exponents  $\alpha, \beta, \gamma > 0$ .

All generalized mass action systems arising from the minimal example have a unique positive steady state.

- Stability of complex balancing equilibria
- Injectivity and multiple general steady states
- Generalized mass action systems and (dynamically) equivalent mass action systems
- Algorithms for sign vector (software for oriented matroids)
- Examples from cell biology

## Thanks!

#### with S. Müller,

Generalized mass action systems: complex balancing equilibria and sign vectors of the stoichiometric and kinetic-order subspaces, *SIAM Journal on Applied Mathematics* **72** (2012), 1926–1947.

with S. Müller, E. Feliu, C. Conradi, A. Shiu, A. Dickenstein, Sign conditions for injectivity of generalized polynomial maps with applications to chemical reaction networks and real algebraic geometry, 2013, 25 pp. Submitted. arXiv:1311.5493 [math.AG]