

Lightweight network interface selection for reliable communications in multi-technologies wireless sensor networks

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### Wireless sensor networks: a tool to help farmers

- •Automate the collection of climate data
- Prevent risks (e.g. frost)
- Decision making (e.g. better use of pesticides)



# Each Radio Access Technology (RAT) have limitations, *e.g.* Sigfox

- Max 12 bytes per message
- Max 140 messages per day
- Limited worldwide coverage



### Many RAT, always a trade-off





### Hard to find the best fitted RAT



### Introducing multi-technologies networks, with multi-RAT nodes

- Multi-RAT multi-hop networks
   Several radio links between two neighbors
   Several use cases (e.g. monitoring, video)
- Need a reliable RAT selection scheme





### Route selection problem: multi attribute decision making

- •A = {Ai, for i=1,2,...,n} the set of candidates
- P = {Pj, for j=1,2,...,m} the set of attributes
- •W = {wj, for j=1,2,...,m} the weights of each attribute

#### MADM DECISION MATRIX

	$P_1$	$P_2$	9	$P_m$
	$w_1$	$w_2$	•••	$w_m$
$A_1$	$x_{11}$	$x_{12}$	•••	$x_{1m}$
$A_2$	$x_{21}$	$x_{22}$		$x_{2m}$
•••	•••		•••	•••
$A_n$	$x_{n1}$	$x_{n2}$	•••	$x_{nm}$

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### Technique for Order Preference by Similarity to Ideal Solution (TOPSIS)

- Ranks each candidate from best to worst
- Ranks are determined based on:
  - closeness to best solution
  - farness to worst solution



## Complexity and ranking abnormalities

- Complex calculations for WSN hardware
- Ranking alteration when removing candidates (e.g. route loss)
- Caused by the euclidean normalization of values





### Lightweight TOPSIS for WSN

- Simple and stable normalization algorithm
- Use fixed bounds for each attribute

Algorithm 1 Lightweight normalization

**Require:**  $x_{ij}$  the raw value of each attribute j for each candidate i

for each attribute  $P_j$  do

if  $P_j$  is an upward attribute then

 $B_j^+$  is the upper bound of  $P_j$ 

 $r_{ij} = \frac{x_{ij}}{B_i^+}$ else if  $P_j$  is a downward attribute then

 $B_j^-$  is the lower bound of  $P_j$ 

 $r_{ij} = \frac{B_j^-}{x_{ij}}$ end if end for return  $r_{ij}$  the normalized value of  $x_{ij}$ 



#### **TOPSIS complexity lowered**

 Spares 5mn-2 operations (with mn the dimensions of the decision matrix)

$$\begin{aligned} r_{ij} &= \frac{x_{ij}}{\sqrt{\sum_{i=1}^{n} x_{ij}^{2}}} \\ A^{+} &= [v_{1}^{+} \dots v_{m}^{+}] \\ A^{-} &= [v_{1}^{-} \dots v_{m}^{-}] \\ v_{j}^{+} &= max\{v_{ij}, i = 1, \dots, n\} \\ v_{j}^{-} &= min\{v_{ij}, i = 1, \dots, n\} \\ v_{j}^{+} &= min\{v_{ij}, i = 1, \dots, n\} \\ v_{j}^{-} &= max\{v_{ij}, i = 1, \dots, n\} \\ v_{j}^{-} &= max\{v_{ij}, i = 1, \dots, n\} \end{aligned}$$

$$S_{i}^{+} = \sqrt{\sum_{j=1}^{m} (v_{j}^{+} - v_{ij})^{2}}$$

$$S_{i}^{-} = \sqrt{\sum_{j=1}^{m} (v_{j}^{-} - v_{ij})^{2}}$$

$$S_{i}^{-} = \sqrt{\sum_{j=1}^{m} (v_{j}^{-} - v_{ij})^{2}}$$

$$S_{i}^{-} = \sqrt{\sum_{j=1}^{m} v_{ij}^{2}}$$



### Hardware for experiments: Pycom Fipy

Allows Python implementation (port of MicroPython)
5 RATs available



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### Lightweight TOPSIS results

- Mean speed up of 39%
  82% NIS similarity with vanilla TOPSIS
- Saves 448µJ per TOPSIS run (based on FiPy data-sheet)



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### Recap & future works

TOPSIS method for multi-criteria selection in WSN
 Custom based method with simpler normalization algorithm
 Quicker execution time for almost identical results, thus energy savings

Plan to use for route selection in multi-technologies routing



### Thank you for your attention! Any questions?

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