



Active matter and hydrodynamic limit for a collective dynamics model

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CMAP, École Polytechnique

CAKE seminar, Cambridge

May 25th 2016



Plan of the talk

Collective motion & Active matter

Collective dynamics

Alignment phase transition

MIPS

Model description

Initial setup

Description of the dynamics

Hydrodynamic limit

Heuristic formulation of the macroscopic limit

Non-gradient hydrodynamics

Irreducibility

Continuous angles dynamic

Active exclusion process

Conclusion



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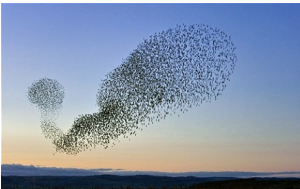
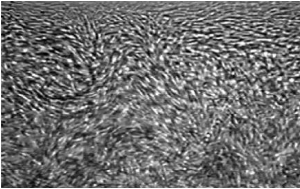
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Collective motion & Active matter

Collective behavior can be observed among numerous animal species

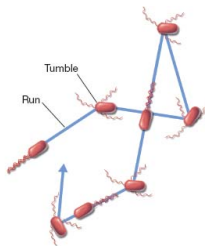




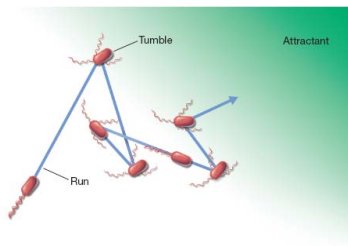
→ Classical representation : *Individual Based Models* (IBM) built around *active matter*.

Active Matter

System composed of many individuals, maintained out of equilibrium by an *energy influx at the individual level*.



(a) No attractant present: Random movement



(b) Attractant present: Directed movement



Two types of phenomena can arise in active matter models :

→ *Alignment phase transition*

→ *Motility Induced Phase Separation (MIPS).*



Alignment phase transition

Alignment

Alignment dynamics will create groups of particles moving together and adapting their speed

Original model by Vicsek&al. (1995, *Novel type of phase transition in a system of self driven particles*)

$\mapsto N = \rho L^2$ particles move in the periodic domain $[0, L]^2$, with speed $v_i(t) = v \vec{e}_{\theta_i(t)}$

$$\begin{cases} x_i(t+1) = x_i(t) + v_i(t)\Delta t \\ \theta_i(t+1) = \langle \theta(t) \rangle_r + \xi_\eta \end{cases}$$



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Numerous results and related models

- *Revisiting the flocking transition using active spins*, Solon & Tailleur, 2013
- *Pattern formation in flocking models: A hydrodynamic description*, Solon & al., 2015

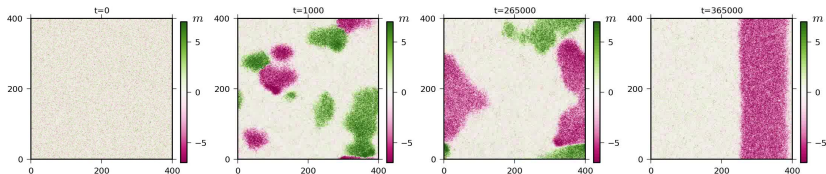


Figure: Emergence of global order for an alignment dynamics. From *Flocking with discrete symmetry, the 2d active Ising model*, Solon & Tailleur 2015.



Exact works

Several analysis and PDE based papers, based on *mean-field interactions* :

↳ Each particle interacts with a large number of neighbors

- *Continuum limit of self-driven particles with orientation interaction*, Degond, Motsch, 2007.
- *Mean field limit for the stochastic Vicsek's model*, Bolley, Carrillo, Canizo, 2011.
- Review on collective motion : *Macroscopic models of collective motion and self organization, review*, Degond & al., 2012



Motility induced phase separation

MIPS

Particles will tend to accumulate where they move more slowly

- MIPS can occur when the particle's velocity depends on the local density
- MIPS usually does not occur in models with alignment : dense clusters tend to quickly align and spread out



- *When are active Brownian particles and run-and-tumble particles equivalent ? consequence for MIPS, Cates & Tailleur 2012*
- *Motility-induced phase separation, Cates & Tailleur 2014*

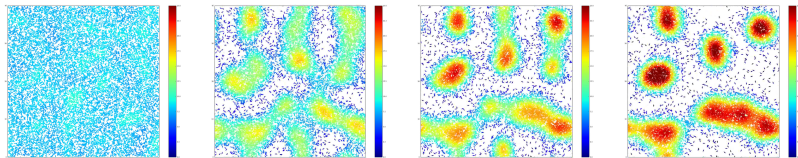


Figure: Coarsening effect in active matter. From Cates & Tailleur 2012.



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Description of the particle system

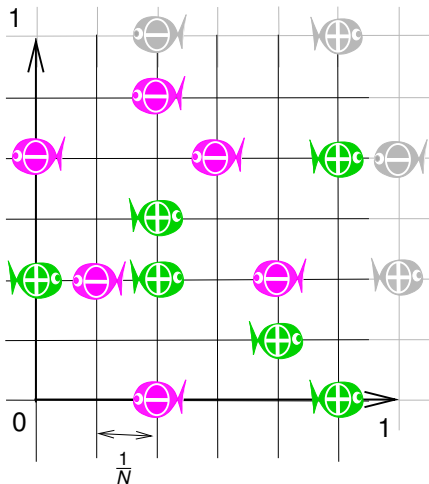
↪ very close to the Active Ising Model (Solon & Tailleur 2015), with at most one particle per site and weak asymmetry.

Two types of particles (+ and -) evolve on the **periodic square lattice** $\mathbb{T}_N^2 = \{0, \frac{1}{N}, \dots, \frac{N-1}{N}\}^2$

- For each site $x \in \mathbb{T}_N^2$, we define $\eta_x \in \{-1, 0, 1\}$.
 - ↪ $\eta_x = 0$ for an empty site
 - ↪ $\eta_x = \pm 1$ for a site occupied by a particle \pm
- We let $\eta_x = \eta_x^+ - \eta_x^-$, where $\eta_x^\pm = 1$ iff x is occupied by a \pm particle.



System configuration



$$\text{Green circle with } + \text{ and tail} : \eta_x^+ = 1$$

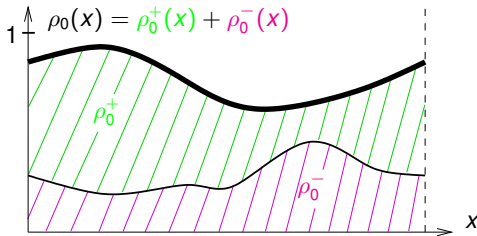
$$\text{Pink circle with } - \text{ and tail} : \eta_x^- = 1$$

$$\text{Grey circle with } + \text{ and tail} : \eta_x^+ = \eta_x^- = 0$$



Initial configuration

- Initial setup : **smooth macroscopic profiles** ρ_0^+ and ρ_0^- , $[0, 1]^2 \rightarrow [0, 1]$.
- $\rho_0 = \rho_0^+ + \rho_0^-$ is the initial particle density



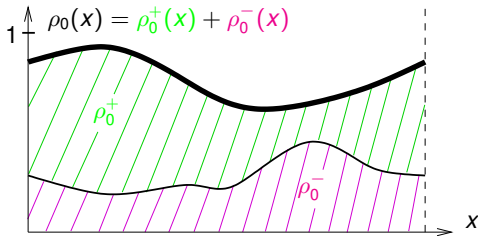
- Initial *local equilibrium* : independently for any $x \in \mathbb{T}_N^2$

$$\eta_x(0) = \begin{cases} \pm 1 & \text{w.p. } \rho_0^\pm(x) \\ 0 & \text{w.p. } 1 - \rho_0^+(x) - \rho_0^-(x) \end{cases}$$



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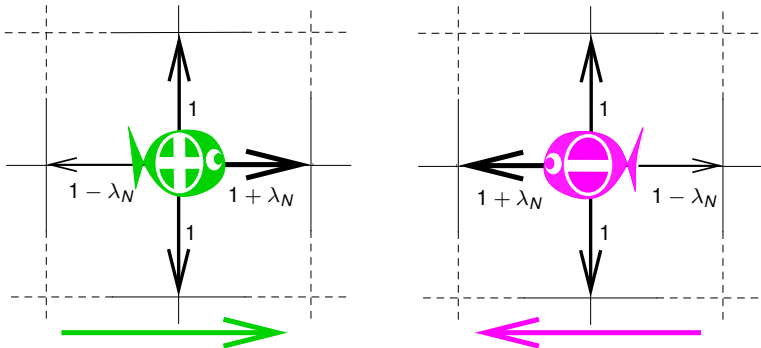


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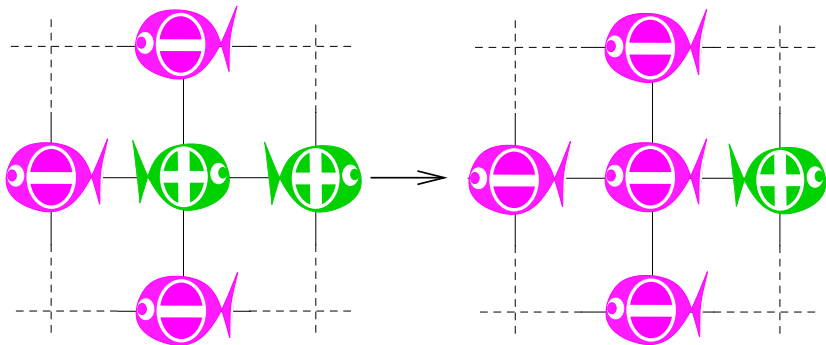
Weakly asymmetric exclusion



- **Exclusion rule** : if the target site is occupied, the motion is canceled
- $\lambda_N = \lambda/N$ is the strength of the **weak asymmetry**



Glauber dynamics



↪ *Ising type* alignment dynamics with inverse temperature β

- $\beta = 0$, no alignment
- $\beta \rightarrow \infty$, strong alignment



Generator of the dynamic

The Markov generator of the process is given by

$$L_N = N^2 \mathcal{L}^S + \lambda N \mathcal{L}^A + \mathcal{L}^G,$$

- \mathcal{L}^S : “generator” of the *Symmetric Simple Exclusion Process* (SSEP)

$$\mathcal{L}^S f(\eta) = \sum_{x \in \mathbb{T}_N} \sum_{|z|=1} |\eta_x| \underbrace{(1 - |\eta_{x+z}|)}_{\text{Exclusion Rule}} (f(\eta^{x, x+z}) - f(\eta)).$$

- Diffusive scaling : $\times N^2$.



Generator of the dynamic

$$L_N = N^2 \mathcal{L}^S + \lambda N \mathcal{L}^A + \mathcal{L}^G,$$

- \mathcal{L}^A : generator of the *Asymmetric Simple Exclusion Process* (WASEP)

$$\mathcal{L}^A f(\eta) = \sum_{x \in \mathbb{T}_N} \sum_{\delta = \pm 1} \delta \eta_x \underbrace{(1 - |\eta_{x+\delta \mathbf{e}_1}|)}_{\text{Exclusion Rule}} \left(f(\eta^{x, x+\delta \mathbf{e}_1}) - f(\eta) \right),$$

- Ballistic scaling : $\times N$.



Generator of the dynamic

$$L_N = N^2 \mathcal{L}^S + \lambda N \mathcal{L}^A + \mathcal{L}^G,$$

- \mathcal{L}^G : generator of the *Glauber alignment dynamics*

$$\mathcal{L}^G f(\eta) = \sum_{x \in \mathbb{T}_N} c_\beta(x, \eta) |\eta_x| (f(\eta^x) - f(\eta)).$$

- One can choose for example

$$c_\beta(x, \eta) = \frac{1}{Z_\beta} \exp \left(-\beta \sum_{y \sim x} \eta_x \eta_y \right).$$

- No need for rescaling.



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Hydrodynamic Limit

Question : Evolution of the macroscopic densities

$$\rho^+, \rho^- : [0, T] \times [0, 1]^2 \rightarrow [0, 1] ?$$

Weak formulation of the macroscopic evolution

For any smooth function H ,

$$\frac{1}{N^2} \sum_{x \in \mathbb{T}_N^2} H(x) \eta_x^+(t) \xrightarrow{N \rightarrow \infty} \int_{[0,1]^2} dx H(x) \rho^+(t, x)$$

and

$$\frac{1}{N^2} \sum_{x \in \mathbb{T}_N^2} H(x) \eta_x^-(t) \xrightarrow{N \rightarrow \infty} \int_{[0,1]^2} dx H(x) \rho^-(t, x).$$



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Heuristic formulation of the macroscopic limit

Theorem

Assumption : $\forall u \in [0, 1]^2, \rho_0(u) = \rho_0^+(u) + \rho_0^-(u) < 1.$

The **macroscopic density** of particles $+$, denoted $\rho^+(t, u)$, is solution **in a weak sense** of the cross reaction-diffusion system

$$\begin{cases} \partial_t \rho^+ = \nabla \cdot [d_s(\rho) \nabla \rho^+ + \partial(\rho^+, \rho) \nabla \rho] + 2\lambda \partial_{x_1} s^+(\rho^+, \rho) + \Gamma_\beta(\rho^+, \rho) \\ \partial_t \rho^- = \nabla \cdot [d_s(\rho) \nabla \rho^- + \partial(\rho^-, \rho) \nabla \rho] + 2\lambda \partial_{x_1} s^-(\rho^-, \rho) - \Gamma_\beta(\rho^+, \rho) \end{cases}$$

with initial condition

$$(\rho^+, \rho^-)(0, x) = (\rho_0^+, \rho_0^-)(x) \quad \forall x.$$

The quantity $\rho = \rho^+ + \rho^-$ is the total particle density.



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J. Quastel.

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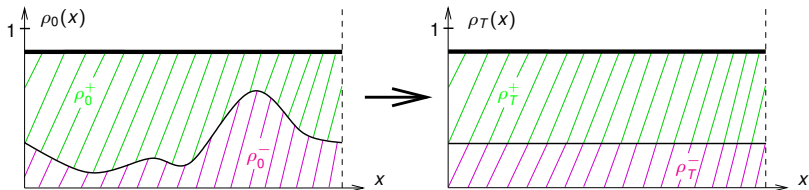
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Scaling limits of interacting particle systems.
 Fundamental Principles of Mathematical Sciences, 1999.



Dynamical interpretation

$$\partial_t \rho^+ = \nabla \cdot \left[d_s(\rho) \nabla \rho^+ + \mathfrak{d}(\rho^+, \rho) \nabla \rho \right] + 2\lambda \partial_{x_1} \mathfrak{s}^+(\rho^+, \rho) + \Gamma_\beta(\rho^+, \rho).$$



d_s is the **self-diffusion coefficient** of a tracer particle in an homogeneous environment.



Self-diffusion coefficient

Setup :

- infinite SSEP on \mathbb{Z}^2 at equilibrium with density $\rho \in]0, 1[$.
- At the origin, we place a *tagged particle*.
- $(X_1(t), X_2(t))$ denotes the position at time t of the tagged particle.

Definition

The *self-diffusion coefficient* is defined by

$$d_s(\rho) = \lim_{t \rightarrow \infty} \frac{\mathbb{E}(X_1(t)^2)}{t}$$

$\mapsto d_s(\rho)$ can be defined by a variational formula (Spohn, 1990).



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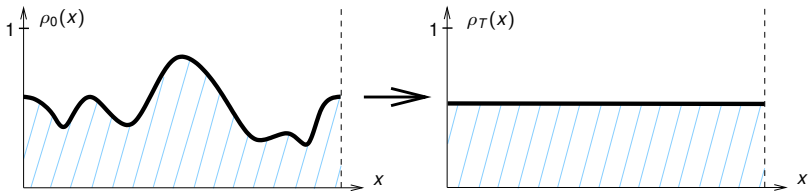
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$$\partial_t \rho^+ = \nabla \cdot \left[d_s(\rho) \nabla \rho^+ + \mathfrak{d}(\rho^+, \rho) \nabla \rho \right] + 2\lambda \partial_{x_1} \mathfrak{s}^+(\rho^+, \rho) + \Gamma_\beta(\rho^+, \rho).$$



The coefficient \mathfrak{d} quantifies the **diffusion** due to heterogeneities of the **total particle density**

$$\mathfrak{d}(\rho^+, \rho) = \frac{\rho^+}{\rho} (1 - d_s(\rho)) \quad (\text{Quastel, 1992}).$$



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↳ The drift terms \mathfrak{s}^+ and \mathfrak{s}^- can be expressed as

$$\mathfrak{s}^+(\rho^+, \rho) = \rho^+ d_s(\rho) + \frac{\rho^+}{\rho} (1 - \rho - d_s(\rho)) (\rho^+ - \rho^-),$$

$$\mathfrak{s}^-(\rho^-, \rho) = -\rho^- d_s(\rho) + \frac{\rho^-}{\rho} (1 - \rho - d_s(\rho)) (\rho^+ - \rho^-),$$

and are linked to \mathfrak{d} and d_s by a matrix Stokes-Einstein relation.



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- Γ_β is the creation rate of "+" particles.
- It depends on the alignment jump rates c_β

Hydrodynamic limit

Empirical measures

$$\pi_t^{+,N} = \frac{1}{N^2} \sum_{x \in \mathbb{T}_N^2} \eta_x^+(t) \delta_x, \quad \text{and} \quad \pi_t^{-,N} = \frac{1}{N^2} \sum_{x \in \mathbb{T}_N} \eta_x^-(t) \delta_x.$$

We want to prove $\pi_t^{+,N} \rightarrow \pi_t^+ = \rho^+(t, x) dx$, i.e. that for any smooth H ,

$$\langle \pi_t^{+,N}, H \rangle \rightarrow \int_{[0,1]^2} \rho^+(t, x) H(x) dx$$

Core principle :

$$\langle \pi_T^{+,N}, H \rangle = \langle \pi_0^{+,N}, H \rangle + \int_0^T L_N \langle \pi_t^{+,N}, H \rangle dt + \underbrace{M_T^N}_{o_N(1)}$$

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Hydrodynamic limit

Assume we are in **one dimension** :

$$\begin{aligned}
 L_N \langle \pi_t^{+,N}, H \rangle &= \frac{1}{N} \sum_{x \in \mathbb{T}_N} H(x) L_N \eta_x^+ \\
 &= \frac{1}{N} \sum_{x \in \mathbb{T}_N} H(x) \left(W_{x-\frac{1}{N}, x} - W_{x, x+\frac{1}{N}} + \gamma_{\beta, x} \right) \\
 &= \frac{1}{N} \sum_{x \in \mathbb{T}_N} \left[\left(H(x) - H\left(x + \frac{1}{N}\right) \right) W_{x, x+\frac{1}{N}} + H(x) \gamma_{\beta, x} \right]
 \end{aligned}$$

and the instantaneous particle current can be written

$$W_{x, x+\frac{1}{N}} = N^2 \underbrace{w_{x, x+\frac{1}{N}}^S}_{\text{symmetric current}} + \lambda N \underbrace{w_{x, x+\frac{1}{N}}^A}_{\text{antisymmetric current}} .$$



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Non-gradient hydrodynamics

- The partial derivative on H balances out a factor N in the current.
- In ***non-gradient systems***, the symmetric current $w_{x, x + \frac{1}{N}}^S$ is not a discrete gradient.
 \mapsto the second integration by parts is not immediate
- One must prove

$$N \cdot w_{x, x + \frac{1}{N}}^S \simeq N \left[d_s(\eta_x^+ - \eta_{x+1}^+) + \vartheta(|\eta_x| - |\eta_{x+1}|) + \mathcal{L}^S f \right]$$



Key steps in the hydrodynamic limit

Additionally to the justification of this replacement, some key points are needed :

- Prove that the measure of the process is "close" to a product measure : *conservation of local equilibrium*
- Introduce *spatial averages*
- Prove a *law of large number for the process*, and replace, for example, the spatial average of $\eta_x^+(t)$ by the density $\rho^+(t, x)$



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Out of equilibrium dynamics

Key issue

Comparison with a product measure on the discrete lattice :

- Distortion of the measure by the Glauber part and the initial configuration are easily controlled
- Distortion by the weak drift, harder to control

⇒ Challenge : prove that the exponential estimates needed in the *non-gradient* method still hold.



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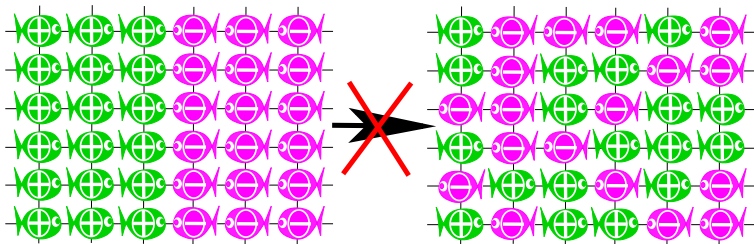
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Irreducibility

Exclusion rule : the process is not always irreducible on canonical ensembles with fixed number and types of particles.





Irreducibility

- One must prove that the dynamics preserves sufficient empty sites spread in the configuration to ensure mixing.
- This was a major issue with the model, which was not present in Quastel's symmetric case.
- Let

$$F_\rho(x) = \{\text{There is no empty site in } B_\rho(x)\},$$

one must in particular prove that

$$\mathbb{E} \left(\frac{1}{N^2} \sum_{x \in \mathbb{T}_N} \mathbb{1}_{F_\rho(x)} \right) \underset{N \rightarrow \infty}{\simeq} \int_{[0,1]^2} dx \rho_x^{|B_\rho|} \xrightarrow{\rho \rightarrow \infty} 0. \quad (1)$$



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Elements on the proof of (1)

The total density $\rho = \rho^+ + \rho^-$ is expected to satisfy

$$\partial_t \rho = \Delta \rho + \lambda \partial_{x_1} (m(1 - \rho)), \quad (2)$$

where $m = (\rho^+ - \rho^-)$ denotes the local "magnetization" of the system.

- Analysis-based proof with microscopic methods, using (2)
- The proof relies on the a-priori control of the density and Gronwall's Lemma



Elements on the proof of (1)

Let $\phi(\rho) = 1/(1 - \rho)$, one can prove, assuming (2), that

$$\partial_t \int_{\mathbb{T}} \phi(\rho_t) dx \leq 2\lambda^2 \int_{\mathbb{T}} \phi(\rho_t) dx$$

⇒ By Gronwall's Lemma, at any time t ,

$$\int_{\mathbb{T}} \phi(\rho_t) dx \leq e^{Ct} \underbrace{\int_{\mathbb{T}} \phi(\rho_0) dx}_{< \infty \text{ by assumption}}.$$

The right-hand side remains finite, therefore the total density cannot reach 1.

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Plan of the talk

Collective motion & Active matter

Collective dynamics

Alignment phase transition

MIPS

Model description

Initial setup

Description of the dynamics

Hydrodynamic limit

Heuristic formulation of the macroscopic limit

Non-gradient hydrodynamics

Irreducibility

Continuous angles dynamic

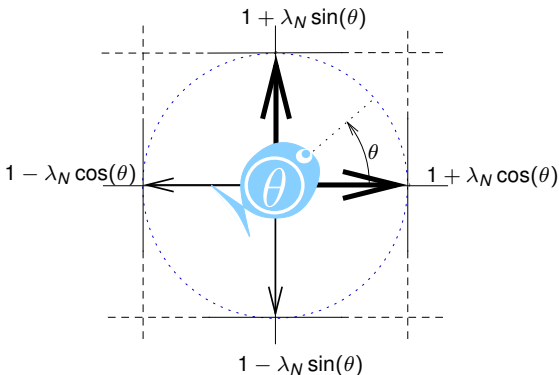
Active exclusion process

Conclusion



Continuous angles dynamic

- The two particle types $+$ and $-$ can be interpreted as angles 0 and π for the drift.
- We now want to extend the proof of the hydrodynamic limit to an angle continuum $\theta \in [0, 2\pi[$.





Main result

The macroscopic density ρ^θ of particles with angle θ , can be “defined” as

$$\frac{1}{N^2} \sum_{x \in \mathbb{T}_N^2} H(x, \theta_x) \eta_x(t) \xrightarrow{N \rightarrow \infty} \int_{[0,1]^2} dx \int_{\theta \in [0, 2\pi[} d\theta H(x, \theta) \rho^\theta(t, x)$$

Theorem (Continuous angles)

Assumption : $\forall x \in [0, 1]^2, \rho_0(x) < 1$.

The “function” $(t, x, \theta) \mapsto \rho^\theta(t, x)$ is solution **in a weak sense** of

$$\partial_t \rho^\theta = \nabla \cdot \left[d_s(\rho) \nabla \rho^\theta + \mathfrak{D}(\rho^\theta, \rho) \nabla \rho \right] + \lambda \nabla \cdot \vec{s}(\rho^\theta, \vec{m}, \rho) + \Gamma_\beta^\theta,$$

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Proof in the continuous case

- Local equilibrium is no longer characterized by a finite number of parameters (e.g. ρ^+ and ρ^-)
- Instead, local equilibrium is characterized by an angle measure on $[0, 2\pi[$: if, locally, one observes 1/3 of empty sites, 1/3 of particles with angle 0 and 1/3 with angle π , the corresponding measure is

$$\hat{\alpha} = \frac{1}{3}\delta_0 + \frac{1}{3}\delta_\pi$$

- This creates several technical difficulties, but the principle of the proof still holds.



Research perspectives

- Replacing metric interactions by topological interactions, typically with the k -nearest neighbors : this should be possible with similar density control tools.
- Large deviations for the system (Macroscopic fluctuations theory)
- Dynamical phase transition (Much harder)



Thanks for your attention !

