

Introduction to Reinforcement Learning

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A Bit of History From Psychology to Machine Learning



The law of effect [Thorndike, 1911]

"Of several responses made to the same situation, those which are accompanied or closely followed by satisfaction to the animal will, other things being equal, be more firmly connected with the situation, so that, when it recurs, they will be more likely to recur; those which are accompanied or closely followed by discomfort to the animal will, other things being equal, have their connections with that situation weakened, so that, when it recurs, they will be less likely to occur.

The greater the satisfaction or discomfort, the greater the strengthening or weakening of the bond."



Experimental psychology

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Remark: **reinforcement** denotes any form of conditioning, either positive (**rewards**) or negative (**punishments**).



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Remark: **reinforcement** denotes the effect of dopamine (and surprise).



Optimal control theory and dynamic programming

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Remark: **reinforcement** denotes an objective function to maximize (or minimize).



Reinforcement learning

Reinforcement learning is learning what to do – how to map situations to actions – so as to maximize a numerical reward signal in an unknown uncertain environment. The learner is not told which actions to take, as in most forms of machine learning, but she must discover which actions yield the most reward by trying them (trial—and—error). In the most interesting and challenging cases, actions may affect not only the immediate reward but also the next situation and, through that, all subsequent rewards (delayed reward).

"An introduction to reinforcement learning", Sutton and Barto (1998).



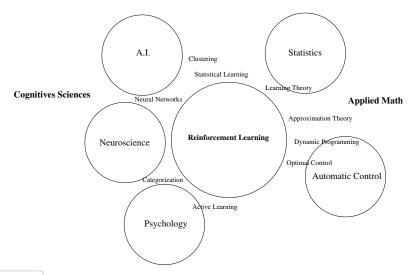
Reinforcement learning







A Multi-disciplinary Field





A Machine Learning Paradigm

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- Unsupervised learning: different objects are clustered together by similarity (e.g., clustering of images on the basis of their content). No actual performance is optimized.
- ► Reinforcement learning: learning by direct interaction (e.g., autonomous robotics). Minimum level of supervision (reward) and maximization of long term performance.



How to *model* an RL problem



How to *model* an RL problem

How to solve exactly an RL problem



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How to solve exactly an RL problem

How to solve incrementally an RL problem



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How to efficiently explore in an RL problem



How to *model* an RL problem

How to solve exactly an RL problem

How to solve *incrementally* an RL problem

How to efficiently explore in an RL problem

How to solve approximately an RL problem



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